FAST I/O MTC-4002

DESCRIPTION



MTC-4002 is a fast counters and interrupts handler card designed to be used in simple applications as well as complex real-time controls.

It is a logic programmable versatile card. It has a generic counters group and other more specifics that cover a wide range of applications. It can still be targeted for specific applications on request.

This card can be used to complement the control of one or more MTC-4031 through the bus. This is useful in applications that require rigorous control of position, speed or shift registers.

Multiple cards can be connected to the same rack.

The setup is done in a simple and intuitive way using graphical software. The access to the counters and fast I/Os is done from CoDeSys programming environment (www.3s-software.com) using function blocks.

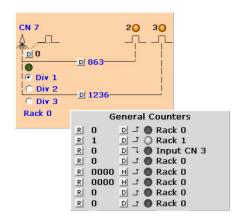
Summary of benefits:

- Shift register oriented eight counter groups
- One counter with eight latched registers
- One counter with tracking and one output
- One counter with tracking and double output
- 1 bit Shift Register with four delayed outputs
- Twelve interruption sources

APPLICATION

The MTC-4002 is mainly used in applications that require accuracy on signal counting and a quick response in real time. Note the flexibility and ease of configuration.

These are some of their applications:

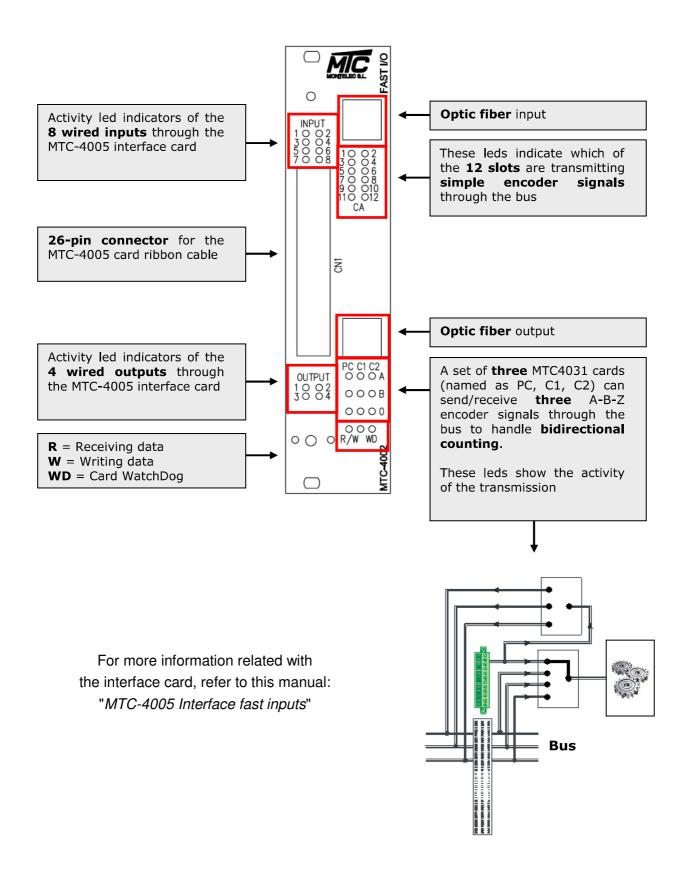


- Incremental / decremental counting
- Angular speed and frequency measurements
- Interrupts generation to the MTC-4000 CPU
- Signal tracking
- Shift registers
- Motor controls with speed or position loops
- System synchronizations
- Signals delay
- Period measurements



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FRONTAL COVER ELEMENTS DESCRIPTION





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TECHNICAL SPECIFICATIONS

Size format
Europe size card
Precision
■ High-speed internal oscillator80MHz
Frontal elements
 1 optic fiber input
Inputs
 Input type
Outputs
 Output type:
Interrupts
 Source quantity
Comunication between cards
 Signal handling between MTC-4002
Counters
 Shift register oriented 8 counter groups
$ \begin{array}{lll} \bullet & \text{One counter with tracking and one output} \\ & \to & \text{Clock source:} & & \text{configurable} \\ & \to & \text{Input source:} & & \text{configurable} \\ \end{array} $
■ Counter for position control with sensor → 1 self-directioned counter X4
Shift Registers
 Register resolution
Filters
$ \begin{array}{lll} & \text{Configurable by program for all elements} & 16 \text{ filters} \\ & \text{Filter } f_{\text{max}} \text{ (clocks)} : & 1,25\text{MHz} \\ & \text{Filter } f_{\text{min}} \text{ (clocks)} : & 38,1469\text{Hz} \\ & \text{Minimum filter pulse width } \text{(I/Os and INTs)} & 400\text{ns} \\ & \text{Maximum filter pulse width } \text{(I/Os and INTs)} & 13,1072\text{ms} \\ \end{array} $

3/3